### Diagnostic Imaging Using Contrast from Fission

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Unknown object





• Interrogate with photons (from the sun)





Measure emitted radiation with an imaging detector (eye)

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- Position sensitive detector
- Known mapping between detector pixel and object voxel
- 4 Diagnostic Imaging Using Contrast from Fission

### **Elements of Imaging**



- Acquire data (e.g., RGB intensities)
- Process detector signals in data acquisition



### **Elements of Imaging**



- Acquire data (e.g., RGB intensities)
- Process detector signals in data acquisition
- Then, do something with the information (e.g., recognize Avneet)









• If Avneet emits radiation, then passive measurements are possible without interrogation



#### **Imaging Fission: Idea**

In principle, the process for imaging fission is the same



#### Object

- Use stimulated or spontaneous fast-neutron emission to indicate fission
- Use collimation of source or detector to achieve mapping between each neutron and a unique path though object

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#### Stimulated Emission: Associated-Particle Technique Using D-T Neutrons



- Interrogate using fast (14 MeV) neutrons produced by the  $d + t \rightarrow \alpha + n$  reaction
- The  $\alpha$  and n are emitted simultaneously in opposite directions
- Detection of the alpha particle determines the time and direction of emitted neutron





## **Experimental Imaging System**





YAP:Ce alpha detector Segmented readout

Left, D-T neutron generator with alpha detector (512 initial neutron directions).





Plastic scintillator block detector. Fast, positionsensitive neutron detectors (3,200 total pixels).

 Imaging system has a D-T neutron generator with alpha detector, highly segmented neutron detectors, and commercial data acquisition system (Siemens Inveon preclinical position emission tomography [PET] system)



## **Stimulated Emission Simulation**





- Instances of stimulated fission identified by detection of multiple late neutrons
- Instances of stimulated fission associated with interrogating neutron direction





### **Stimulated Emission Backgrounds**

0 ns

 Fission competes with other reaction backgrounds as well as scattering between detectors







- Almost all materials yield some amount of late-arriving singles and doubles from incident 14-MeV neutrons
- Estimate of yield for all materials from tabulated (n,nγ), (n,np), (n,nd), (n,nt), (n,n<sup>3</sup>He), (n,nα), (n,n2p), (n,npα), (n,n2α), (n,nd2α), (n,nt2α), (n,n3α), and (n,f) cross sections in evaluated nuclear data



#### **Example Experimental Data (1)**



 Photographs and projection data where transmission is shown in grayscale, induced neutron doubles are shown in red, and hydrogen scatter is shown in blue



#### **Example Experimental Data (2)**



 Photographs and projection data where transmission is shown in grayscale, induced neutron doubles are shown in red, and hydrogen scatter is shown in blue



#### **Example Experimental Data (3)**



 Photographs and projection data where transmission is shown in grayscale, induced neutron doubles are shown in red, and hydrogen scatter is shown in blue



#### **Reconstructed Images of (3)**



Object

Transmission

Fission (neutron doubles)

• Tomographic reconstruction of induced neutron doubles (fission) identifies depleted uranium (DU) storage casting



#### 18 kg HEU or DU

3 DU shields

#### **Transmission**

#### **Doubles**

#### Combined

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- Fission imaging can identify HEU, even shielded by DU
- Not distinguishable via transmission measurements







Measuring at Y-12



**Shielded HEU** 



# **Shielded HEU**



- Idaho National Laboratory inspection object (IO) #7 contains HEU (yellow) shielded by DU (black/gray)
- Induced-fission tomography identifies HEU portion



### **Emission Tomography**

- ORNL developing a new capability to perform passive fast-neutron emission tomography for spent nuclear fuel
- Why? To support item accountability by verifying the integrity of spent fuel assemblies before transfer to difficult to access storage
- Challenges
  - Sufficient spatial resolution to identify individual fuel pins
  - Sufficient efficiency to measure on an appropriate time scale (~1 h)
  - Sufficient insensitivity to gamma rays to handle the relevant gamma dose rates





### **Present Integrity Verification**



- Primary tools for verifying assemblies are the Digital Cherenkov Viewing Device (DCVD) and fork detector (FDET)
  - DCVD provides quantitative measure of amount of Cherenkov light induced in water channels between fuel rods
  - FDET measures combined total gamma and neutron activity



#### **Present Integrity Verification**



"The major common weaknesses of the DCVD and FDET is that **the detection probability is null** for carefully designed low-level diversions of a few fuel rods in each fuel assembly within a large population." –A. Lebrun, IAEA Nondestructive Analysis Section Head

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#### **Basis of Verification Using Neutron Imaging**

0.00018

0.00016

0.00014

0.00012

0.0001 0.00008 0.00006 0.00004 0.00002

0

0

10

Atoms/ba



- Verifying integrity (i.e., all fuel pins are present)
- Use fast neutrons (primarily from <sup>244</sup>Cm spontaneous fission)
- Neutron intensity as a function of burnup gives sensitivity to replacement pins that are subsequently irradiated

NOT confirming Pu

20

30

Burnup (GWd/MTU)

 Pu content only known to a few percent from burnup codes

40

50

60

 Pu content saturates with exposure (minimally sensitive to pin replacements made after first cycle in reactor)



#### Imaging Approach

- Imaging (emission tomography) fully uses available information to account for complicated geometries and identify emissions from individual fuel pins.
- Would you detect the absence of a single star in the night sky by measuring the total brightness of the night sky?



http://rsaa.anu.edu.au/news-events/mt-stromlo-observatory-public-astronomy-nights-5

• Fast neutrons enable penetration of high-atomic number shielding to verify an entire volume rather than its surface, providing the highest sensitivity to diversion with subsequent irradiation of substituted pins. OAK RIDGE National Laboratory



- Imaging depends on isolating lines of response through an object, where neutrons originate along a known path
  - Achieved via collimation
- Expect the scale of the collimator to be ~30 cm thick (will not work if substantially smaller)





- To work, detector pixels and collimator slit spacing need to be large (~5 cm), especially for moderated detectors
- Two conventional options: parallel slit requires scanning, pinhole requires lacksquarelarge size OAK RIDGE National Laboratory

## **Novel Collimator Design**

There is a non-scanning and compact design option that uses many detectors



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 Equivalent to a parallel slit collimator, but each slit position is rotated to distribute endpoints evenly over outer diameter to make space for large detectors and spacing between slits

#### **Parallel-slit versus Radial Collimator**



• Acquires same data as parallel-slit collimator but in a different order



#### **Imager Concept**

- Steel and borated polyethylene (BP) collimator with 100 slits to isolate lines of response
- Stainless steel (SS) for structural integrity and shield detectors from gammas
- Annulus of 100 detectors that wrap around the fuel detects neutrons
- Fuel and detectors stationary, collimator rotates to perform tomography
- Annular design gives compact size



#### **Radiation resistant**

Boron straw detectors (instrumented singly) can handle fields as high as 1,000 R/h

#### Efficient

- Large detectors
- Close to source
- No scanning, all lines of response measured simultaneously



## **Point-source Response**



 Performance of collimator encoded in the point spread function (PSF) that quantifies line of response to a point source

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 Vary slit width, collimator materials, and collimator thickness to maximize signal to noise ratio (SNR) for individual pins

## **Point-source Response**



- Resolution is limited by slit width, slit bore scattering, and scattering in detectors
- Dominant limitation is scattering of neutrons into neighboring detectors before capture



### **Point-source Response**



- SNR is limited by penetration of the collimator
- Note all (264 pins) contribute to background
- Additional background from nearby pins and poor resolution





- SNR depends on the PSF
  - Goes to 0 with a collimator that is too thin (no modulation) or too thick (no counts)
  - Goes to 0 with slits that are too wide (no resolution) or too narrow (no counts)
  - Somewhere in the middle is optimal
- SNR estimate's assumptions
  - 2.55 × 10<sup>5</sup> n/s/m/fuel pin
  - Neglects scatter and self-attenuation within the spent fuel assembly



#### **Sample Reconstruction of Five Sources**



Calculated Sinogram



Measured Sinogram



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#### Calculated PSF is consistent with resolving neighboring fuel pins (40 GWd/tU, 10 min)

#### **Reconstruction of Many Sources**



# Calculated Sinogram



#### **Measured Sinogram**





 Calculated PSF is consistent with identifying missing fuel pins









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