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Nuclear Fission in Monte Carlo Particle Transport Simulations

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Monte Carlo computer codes have been used to simulate neutron transport in fissionable materials since the late 1940s. Today's MC codes such as MCNP6 can accurately model nearly any geometry and make use of detailed physics interaction data from the ENDF/B- VII libraries. For many applications today, many billions of neutrons are simulated using MC methods on parallel computers. While MC methods for neutron transport can be viewed in practical terms (i.e., just simulate particle behavior), there is a solid mathematical and physical basis founded in the linear Boltzmann transport equation. This lecture provides an overview of MC methods for simulating particle transport, with particular emphasis on the fundamental assumptions in the underlying equations and transport and collision modeling. Depending on the application, some portions of the simulations may use expected-value outcomes, while other portions require detailed modeling that conserves energy, momentum, particles, correlations, etc. Static eigenvalue calculations are compared with fixed-source time dependent approaches, and the detailed modeling of fission processes in MCNP is reviewed.



- Introduction
- Monte Carlo simulation and the transport equation
 - Overview, particle simulation, theory, assumptions
 - Eigenvalue problems vs. fixed-source time dependent problems
- Using expected-value outcomes vs. detailed modeling
 - Analog vs weighted simulation
 - Transport process and Doppler broadening
 - Collision physics and particle production
- Fission process modeling in MCNP
 - Expected-value approach for eigenvalue calculations
 - Detailed modeling of multiplicity and correlated particle production
 - Spontaneous vs. induced fission
 - Emission spectra



Introduction

Monte Carlo & MCNP History





ENIAC – 1945

30 tons 20 ft x 40 ft room 18,000 vacuum tubes 0.1 MHz 20 word memory patchcords

Manhattan Project – 1945...

Discussions on using ENIAC Ulam suggested using the "method of statistical trials" Metropolis suggested the name "Monte Carlo" Von Neumann developed the first computer code



MCNP6 Features





mcnp5 – 100 K lines of code mcnp6 – 500 K lines of code



HEU-MET-THERM-003



Figure 2. Array of 0.5-in. Cubes Prior to Immersion.

Zeus-2, HEU-MET-INTER-006, case 2



PU-MET-FAST-003, case 3



IEU-COMP-THERM-002, case 3



Figure 9. Model of Conc. (dimension is not over dimension is not over dimension is not over dimension in the state of the



Figure 7. Fuel Loading for PNL-31 and PNL-33.

MCNP & Nuclear Criticality Safety (2)





Figure 1. Unreflected HEU Sphere, heu-met-fast-008





Figure 4. HEU Sphere Reflected by Polyethylene, heu-met-fast-011



e 5. Incomplete HEU Sphere Reflected by Aluminum, heu-met-fast-012

Figure 2. Incomplete HEU Sphere Reflected by Beryllium, heu-met-fast-009-case-1

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MCNP & Reactors (1) - PWR Analysis



Whole-core Thermal & Total Flux from MCNP5 Analysis



Assembly Thermal & Fast Flux from MCNP5 Analysis



(from Luka Snoj, Jozef Stefan Inst.)

MCNP & Reactors (2) - TRIGA Reactor LEU Conversion







Monte Carlo Simulation & the Transport Equation





During analysis of both flights & collisions, tally information about distances, collisions, etc. to use later in statistical analysis for results



- After a particle emerges from source or collision, or if the particle is entering a new cell:
 - Randomly sample the free-flight distance to the next interaction
 - If distance-to-interaction < distance-to-boundary,
 then move the particle to the interaction point
 - Collision physics at the interaction point:
 - Determine which isotope the interaction is with
 - Determine which reaction type for that isotope
 - Determine the exit energy & direction of the particle
 - Determine if secondary particles were produced
 - Biasing + weight adjustments
 - Tallies of quantities of interest



- Given a particle in a cell containing material M, sample the free-flight distance to the next interaction
 - Σ_T = total macroscopic cross-section in material M
 = probability of any interaction per unit distance, units cm⁻¹

$$\Sigma_T(E) = \sum_{k}^{\text{nuclides}} N^k \cdot \sigma_T^k(E)$$

- PDF for flight distance s, where $0 \le s \le \infty$,

$$f(s) = \Sigma_{T} exp(-\Sigma_{T} s)$$

- Sampling procedure

$$F(s) = 1 - exp(-\Sigma_T s) \rightarrow s = - ln(\xi) / \Sigma_T$$



•
$$\Sigma_T = \sum_k N^k \sigma_T^k$$
 where $k = isotopes in material M$

Probability that collision is with isotope J



- { p_J } = set of discrete probabilities for selecting collision isotope
- { P_J } = discrete CDF, $P_J = \sum_{k=1}^{J} p_k$
- Discrete sampling for collision isotope k table search to determine k such that P_{k-1} ≤ ξ < P_k



• For collision isotope k,

$$\sigma_{T} = \sigma_{elastic} + \sigma_{inelastic} + \sigma_{capture} + \sigma_{fission} + \dots$$

- $p_J = \sigma_J / \sigma_T$ = probability of reaction type J for isotope k
- { p_J} = set of discrete probabilities for selecting reaction type J
- { P_J } = discrete CDF, $P_J = \sum_{k=1}^{J} p_k$
- Discrete sampling for reaction type J table search to determine J such that P_{J-1} ≤ ξ < P_J



- Given a collision isotope k & reaction type j, the random sampling techniques used to determine the exit energy and direction, E' and (u',v',w'), depend on
 - Conservation of energy & momentum
 - Scattering laws either equations or tabulated data

• Examples

- Isotropic scattering in lab system
- Elastic scattering, target-at-rest
- Elastic scattering, free-gas model
- Inelastic scattering
- $S(\alpha,\beta)$ thermal scattering
- Other collision physics, MCNP



- Law 1 ENDF law 1 Equiprobable energy bins
- Law 2 Discrete photon energies
- Law 3 ENDF law 3 Inelastic scatter from nuclear levels
- Law 4 ENDF law 4 Tabular distribution
- Law 5 ENDF law 5 General evaporation spectrum
- Law 7 ENDF law 7 Simple Maxwell fission spectrum
- Law 9 ENDF law 9 Evaporation spectrum
- Law 11 ENDF law 11 Energy dependent Watt spectrum
- Law 22 UK law 2 Tabular linear functions of incident energy out
- Law 24 UK law 6 Equiprobable energy multipliers
- Law 44 ENDF law 1, lang 2, Kalbach-87 correlated energy-angle scatter
- Law 61 ENDF law 11, lang 0,12, or 14 correlated energy-angle scatter
- Law 66 ENDF law 6 N-body phase space distribution
- Law 67 ENDF law 7 correlated energy-angle scatter



- Emission from fission
- Delayed neutron emission
- $S(\alpha,\beta)$ scattering for thermal neutrons
- Free-gas scattering for neutrons
- Probability tables for the unresolved resonance energy range
- Photon interactions
 - Photoelectric effect
 - Pair production
 - Compton scattering (incoherent)
 - Thomson scattering (coherent)
 - Fluorescent emission
 - Photonuclear reactions
- Electron interactions condensed history approach
 - Stopping power, straggling, angular deflections
 - Bremsstrahlung
 - K-shell impact ionization & Auger transitions
 - Knock-on electrons



Assume:

- Neutrons & photons are particles, not waves
- Particles move in a straight line between collisions (neutrons, photons)
- Collisions occur instantaneously, at a point in space
- Particle speeds are small enough to neglect relativistic effects
- Particle speeds are high enough to neglect quantum effects
- Particle collisions do not change the properties of a material (ie, no feedback, no material heating, no depletion)

Why?

- Want to solve the linear Boltzmann transport equation
- Want to apply the superposition principle
- Want the Central Limit Theorem to apply for computing statistics
 - Statisticians love the term "IID" Independent, Identically Distributed

(Any or all of the above assumptions can be relaxed, with careful analysis & extra computing cost.)



 Time-dependent linear Boltzmann transport equation for neutrons, with prompt fission source & external source

 $\frac{1}{v} \frac{\partial \psi(\vec{r}, E, \vec{\Omega}, t)}{\partial t} = \begin{array}{c} \text{External source} & \text{Scattering} \\ Q(\vec{r}, E, \vec{\Omega}, t) + \iint \psi(\vec{r}, E', \vec{\Omega}', t) \Sigma_{s}(\vec{r}, E' \rightarrow E, \vec{\Omega} \cdot \vec{\Omega}') d\vec{\Omega}' dE' \end{array}$

$$+ \frac{\chi(\vec{r},E)}{4\pi} \iint v\Sigma_{F}(\vec{r},E')\psi(\vec{r},E',\vec{\Omega}',t)d\vec{\Omega}'dE'$$

Leakage Collisions $-\left[\vec{\Omega} \cdot \nabla + \Sigma_{T}(\vec{r},E)\right] \cdot \psi(\vec{r},E,\vec{\Omega},t)$

$$\frac{1}{v} \frac{\partial \psi(\vec{r}, E, \vec{\Omega}, t)}{\partial t} = Q + [S + M] \cdot \psi - [L + T] \cdot \psi$$

Gains Losses

- This equation can be solved directly by Monte Carlo, assuming:
 - Each neutron history is an IID trial (independent, identically distributed)
 - All neutrons must see same probability densities in all of phase space
 - Usual method: geometry & materials fixed over solution interval ∆t



- Derive integral equation, in kernel form
 - Start with integro-differential equation
 - Use integrating factor $\exp\left[-\int_{0}^{R} \Sigma_{T}(\vec{r} R\hat{\Omega}, E) dR'\right]$, where $R\hat{\Omega} = \vec{r} \vec{r'}$
 - Define

$$\vec{E} = E \cdot \hat{\Omega}$$

Collision density: $\Psi(\vec{r},\vec{E}) = \Sigma_T(\vec{r},E) \cdot \psi(\vec{r},\vec{E})$

Transport kernel: $T(\vec{r}' \to \vec{r}, \vec{E}) = \Sigma_T(\vec{r}, E) \cdot \exp\left[-\int_{0}^{|\vec{r} - \vec{r}'|} \Sigma_T(\vec{r}' + s\hat{\Omega}, E) ds\right] \cdot \frac{\delta(\hat{\Omega} \cdot \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^2})}{|\vec{r} - \vec{r}'|^2}$ **Collision kernel:** $C(\vec{E}' \to \vec{E}, \vec{r}) = \frac{\Sigma_S(\vec{r}, \vec{E}' \to \vec{E})}{\Sigma_T(\vec{r}, E')} + \frac{\chi(E)v\Sigma_F(\vec{r}, E')}{4\pi \cdot \Sigma_T(\vec{r}, E')}$

– Then

$$\Psi(\vec{r},\vec{E}) = \int \left[\int \Psi(\vec{r}',\vec{E}') \cdot C(\vec{E}' \to \vec{E},\vec{r}') d\vec{E}' + Q(\vec{r}',\vec{E}') \right] \cdot T(\vec{r}' \to \vec{r},\vec{E}) d\vec{r}'$$

Reference: D.C. Irving, "The Adjoint Boltzmann Equation and Its Simulation by Monte Carlo" Nuclear Engineering & Design **15**, 273-292 (1971)



Basis for the Monte Carlo Solution Method

$$\Psi(\vec{r},\vec{E}) = \int \left[\int \Psi(\vec{r}',\vec{E}') \cdot C(\vec{E}' \to \vec{E},\vec{r}') d\vec{E}' + Q(\vec{r}',\vec{E}') \right] \cdot T(\vec{r}' \to \vec{r},\vec{E}) d\vec{r}'$$

Let
$$p = (\vec{r}, \vec{E})$$
 and $R(p' \rightarrow p) = C(\vec{E}' \rightarrow \vec{E}, \vec{r}') \cdot T(\vec{r}' \rightarrow \vec{r}, \vec{E})$

Expand Ψ into components having 0,1,2,...,k collisions

$$\Psi(p) = \sum_{k=0}^{\infty} \Psi_k(p), \quad \text{with} \quad \Psi_0(p) = \int Q(\vec{r}', \vec{E}) \cdot T(\vec{r}' \to \vec{r}, \vec{E}) d\vec{r}'$$

By definition,

$$\Psi_{k}(p) = \int \Psi_{k-1}(p') \cdot R(p' \rightarrow p) dp'$$

Markovian: collision k depends only on the results of collision k-1, and not on any prior collisions k-2, k-3, ...



Histories

• After repeated substitution for Ψ_k

$$\Psi_{k}(p) = \int \Psi_{k-1}(p') \cdot R(p' \to p) dp'$$

= $\int ... \int \Psi_{0}(p_{0}) \cdot R(p_{0} \to p_{1}) \cdot R(p_{1} \to p_{2}) ... R(p_{k-1} \to p) dp_{0} ... dp_{k-1}$



 For estimates in a given region, <u>tally</u> the occurrences for <u>each collision of each "history"</u> within a region



$$\Psi_{k}(p) = \int \dots \int \Psi_{0}(p_{0}) \cdot R(p_{0} \rightarrow p_{1}) \cdot R(p_{1} \rightarrow p_{2}) \dots R(p_{k-1} \rightarrow p) dp_{0} \dots dp_{k-1}$$

Monte Carlo approach:

- Generate a sequence of states (p₀, p₁, p₂, p₃,) [i.e., a history] by:
 - Randomly sample from PDF for source: $\Psi_0(p_0)$
 - Randomly sample from PDF for k^{th} transition: $R(p_{k-1} \rightarrow p_k)$
- Generate estimates of results by averaging over states for M histories:

$$A = \int A(p) \cdot \Psi(p) dp \approx \frac{1}{M} \cdot \sum_{m=1}^{M} \left(\sum_{k=1}^{\infty} A(p_{k,m}) \right)$$



Random Walk for Particle



Fixed-source Monte Carlo Calculation







- For problems with fission multiplication, another approach is to create a static eigenvalue problem from the time-dependent transport equation (the asymptotic or steady-state solution)
- Introduce K_{eff}, a scaling factor on the multiplication (v)
- Assume:
 - 1. Fixed geometry & materials
 - 2. No external source: $Q(r,E,\Omega,t) = 0$
 - 3. $\partial \Psi / \partial t = 0$: $v \Rightarrow v / k_{eff}$
- Setting $\partial \Psi / \partial t = 0$ and introducing the K_{eff} eigenvalue gives

$$\left[L+T\right]\Psi_{k}(\vec{r},E,\vec{\Omega}) = \left[S+\frac{1}{K_{eff}}M\right]\Psi_{k}$$

- Steady-state equation, a static eigenvalue problem for K_{eff} and Ψ_k
- K_{eff} = effective multiplication factor
- K_{eff} and Ψ_k should never be used to model time-dependent problems.



$$[L+T]\Psi_{k} = [S + 1/kM]\Psi_{k}$$

- The factor 1/k changes the relative <u>level</u> of the fission source, to balance the equation & permit a <u>steady-state solution</u>
- Criticality

Supercritical:	K _{eff} > 1
Critical:	$K_{eff} = 1$
Subcritical:	K _{eff} < 1

Monte Carlo Eigenvalue calculation





Iterate (cycle) until converged, then more to accumulate tallies



Using Expected-value Outcomes vs Detailed Modeling



- Monte Carlo methods evaluate integrals using random sampling
 - Random sampling introduces variance (noise) into the results
 - More random sampling in the simulation -> more variance
- Statistical weights for particles can be used to permit replacing the random sampling of an event by the expected value for the event



Random selection of scatter vs absorb. Estimate absorption for N collisions:

```
S = 0
For k = 1 ... N {
if \xi > \sigma_S / \sigma_T then S += 1
}
Absorption = S / N + statistical noise
```



Always scatter, with reduced wgt. Estimate absorption for N collisions:

Absorption = $[N \cdot (1 - \sigma_s / \sigma_T)] / N = \sigma_s / \sigma_T$

Replacing random sampling of an event by the expected value eliminates the variance contribution from the event.



• Doppler broadening

- For neutron flights through a material, we don't randomly sample target nuclide velocity for the ~ 10^{20} nuclides in the flight path
- We average the target nuclide cross-sections over a Maxwellian distribution of nuclide velocities, and use the average cross-section to determine the flight distance

Criticality safety & reactor physics

- We routinely use "implicit capture", where neutrons always survive a collision with weight reduced by σ_s / σ_T
- Some codes (not MCNP) model n-2n by scattering and multiply neutron weight by 2.
- For neutrons produced by fission, routinely use expected value of wgt $\cdot v \Sigma_F / \Sigma_T$ neutrons per collision
- For photon production, routinely use wgt $\sigma_{n\to\gamma}/\sigma_T$ photons produced per collision
- → Use of expected values implies <u>un</u>correlated outcomes



- In many applications, survival biasing is an effective variance • reduction technique
 - Survival biasing is also called implicit absorption, nonabsorption weighting, or (loosely) implicit capture
 - (absorption = disappearance) - $\Sigma_{\rm T} = \Sigma_{\rm absorption} + \Sigma_{\rm scatter}$
 - Probability that particle survives collision = $P_{surv} = \Sigma_{scatter} / \Sigma_T$
 - Probability that particle is absorbed (killed) = $1 P_{surv}$
- **Disallow absorption of particle, & then adjust particle weight to** • ensure a fair game
 - Tally absorption of wgt · (1-P_{surv})
 - Multiply particle weight by P_{surv}
 - When selecting collision isotope: use Σ_s 's, not Σ_T 's for isotopes
 - When selecting reaction type: don't include σ_A



- Consider a collision which results in fission
 - wgt $\cdot \nu \Sigma_{\rm F} / \Sigma_{\rm T}$ = expected number of fission neutrons produced per collision
- To sample the number of neutrons produced in the collision

- Let
$$r = wgt \cdot \nu \Sigma_F / \Sigma_T$$

 $n = int[r]$

- Then, Produce n fission neutrons with probability 1, and an additional fission neutron with probability r-n
- Example: wgt $\cdot \nu \Sigma_{\rm F} / \Sigma_{\rm T} = 1.75$

If $\xi < .75$, produce 2 neutrons, otherwise produce 1 or Produce int[1.75 + ξ] neutrons



Fission Process Modeling in MCNP6

Background



• Terrell

- probability for producing n fission neutrons

$$P_{0} = \frac{1}{\sqrt{2\pi\sigma^{2}}} \int_{-\infty}^{1/2} \exp(\frac{-(x-\overline{v}+b)^{2}}{2\sigma^{2}}) dx ,$$
$$P_{n\neq0} = \frac{1}{\sqrt{2\pi\sigma^{2}}} \int_{n-1/2}^{n+1/2} \exp(\frac{-(x-\overline{v}+b)^{2}}{2\sigma^{2}}) dx$$

- Random sampling from a continuous Gaussian is easy
- Converting to integer is trivial, but does not preserve moments
- b = small adjustment, to preserve correct nu-bar
- Traditional MCNP6 options differ only in schemes for sampling a Gaussian, converting to integer, & adjusting to preserve nu-bar
- Measured data
 - Terrell
 - Zucker, Holden
 - Gwin, Spencer, Ingle
- Lestone method based on preserving moments



For criticality calculations

[no external source, no spontaneous fission]

- Neutron multiplicity for fission is based on expected value of $wgt \cdot v \Sigma_F^{mat} / \Sigma_T^{mat}$ neutrons per collision in the material
 - If more than 1 neutron, the energy & direction for each are sampled independently (no correlation)
- The spectrum used for the fission neutrons is randomly chosen using probabilities $v \Sigma_F^{iso} / v \Sigma_T^{mat}$ for the nuclides in the material
 - Energy is sampled using ENDF spectrum data for the selected nuclide
 - Prompt vs delayed neutron selected first, then energy
 - If more than 1 neutron, energy is sampled independently for each one (no correlation), using the same spectrum data
- The direction for fission neutrons is sampled isotropically
 - If more than 1 neutron, directions are sampled independently for each neutron (no correlation in direction)
- For KCODE problems with photons, photons are sampled independent of neutrons (no correlation between neutrons & photons)



- Why is the expected value approach to fission neutron production used for criticality calculations? Why not use explicit fission neutron multiplicity data?
 - Traditional MC work in the criticality safety community has focused on k-effective, reflector & control material reactivity, etc.
 - The reactor physics community has traditionally used MC for keffective, power distributions, control material reactivity, etc.
 - Very extensive collections of verification-validation data, MC vs benchmark experiments for those applications
 - No verification-validation work has been done to date on using explicit fission neutron multiplicity options in MCNP for criticality safety or reactor physics applications



- For fixed-source problems, MCNP6 has a variety of options for treating fission neutron multiplicity
- FMULT input card sets the option for each fissionable nuclide:
 - Spontaneous fission:
 - Multiplicity: nu-bar + Gaussian width **or** 10-bin distribution
 - Spectrum: Watt spectrum
 - Induced fission:
 - MCNP traditional, based on expected value, $v \Sigma_{F}^{mat} / \Sigma_{T}^{mat}$
 - Explicit multiplicity model options:
 - Method
 - » Lestone model (based on fits to moments)
 - » Ensslin/Santi/Beddingfield/Mayo model
 - » LLNL fission package (many options)
 - Data
 - » Terrell
 - » Lestone
 - » Ensslin/Santi/Beddingfield/Mayo
 - Shift
 - » Various options, preserves nu-bar (needed when sampling integers from continuous distribution)



fission multiplicity data.

zaid	width	watt1	watt2	yield	sfnu	CDF for number of neutrons								
90232	1.079	.800000	4.00000	6.00E-08	2.140									
92232	1.079	.892204	3.72278	1.30E+00	1.710									
92233	1.041	.854803	4.03210	8.60E-04	1.760									
92234	1.079	.771241	4.92449	5.02E-03	1.810									
92235	1.072	.774713	4.85231	2.99E-04	1.860									
92236	1.079	.735166	5.35746	5.49E-03	1.910									
92238	1.230	.648318	6.81057	1.36E-02	0.048	.297	.722	.950	.993	1.00	1.00	1.00	1.00	1.
93237	1.079	.833438	4.24147	1.14E-04	2.050									
94236	0.000	.000000	0.00000	0.00E+00	0.080	.293	.670	.905	.980	1.00	1.00	1.00	1.00	1.
94238	1.115	.847833	4.16933	2.59E+03	0.056	.267	.647	.869	.974	1.00	1.00	1.00	1.00	1.
94239	1.140	.885247	3.80269	2.18E-02	2.160									
94240	1.109	.794930	4.68927	1.02E+03	0.063	.295	.628	.881	.980	.998	1.00	1.00	1.00	1.
94241	1.079	.842472	4.15150	5.00E-02	2.250									
94242	1.069	.819150	4.36668	1.72E+03	0.068	.297	.631	.879	.979	.997	1.00	1.00	1.00	1.
95241	1.079	.933020	3.46195	1.18E+00	3.220									
96242	1.053	.887353	3.89176	2.10E+07	0.021	.168	.495	.822	.959	.996	.999	1.00	1.00	1.
96244	1.036	.902523	3.72033	1.08E+07	0.015	.131	.431	.764	.948	.991	1.00	1.00	1.00	1.
96246	0.000	.000000	0.00000	0.00E+00	0.015	.091	.354	.699	.917	.993	1.00	1.00	1.00	1.
96248	0.000	.000000	0.00000	0.00E+00	0.007	.066	.287	.638	.892	.982	.998	1.00	1.00	1.
97249	1.079	.891281	3.79405	1.00E+05	3.400									
98246	0.000	.000000	0.00000	0.00E+00	0.001	.114	.349	.623	.844	.970	1.00	1.00	1.00	1.
98250	0.000	.000000	0.00000	0.00E+00	0.004	.040	.208	.502	.801	.946	.993	.997	1.00	1.
98252	1.207	1.180000	1.03419	2.34E+12	0.002	.028	.153	.427	.733	.918	.984	.998	1.00	1.
98254	0.000	.000000	0.00000	0.00E+00	0.000	.019	.132	.396	.714	.908	.983	.998	1.00	1.
100257	0.000	.000000	0.00000	0.00E+00	0.021	.073	.190	.390	.652	.853	.959	.993	1.00	1.
102252	0.000	.000000	0.00000	0.00E+00	0.057	.115	.207	.351	.534	.717	.863	.959	.997	1.

MCNP6 – Induced Fission Neutron Multiplicity Options



 Overly complicated – a result of recent merging of MCNP5 & MCNPX multiplicity treatments

```
Comments from the MCNP6 routine acenus.F90:
   ! Integer variable if isnu determines the fission multiplicity
   ! dataset for sampling the Gaussian width.
       ifisnu = abc
   1
         c = 1 Lestone data
   1
         c = 2 Terrell data
   1
         c = 3 Ensslin, Santi, Beddingfield, Mayo data
   1
         b = 0 MCNP5 shift to preserve nubar
   1
         b = 1 MCNPX shift to preserve nubar
   b = 2 MCNPX threshold shift to preserve nubar
   1
         b = 3 MCNPX no shift to preserve nubar
   b = 4 MCNPX nearest integer but with multiplicity prints
   1
         a = 0 MCNP5 normal dist sc Gaussian sampling
   1
         a >= 1 MCNPX normal dist po Gaussian sampling
   1
   1
         a \ge 2 MCNPX nu = nu + rang(), not MCNP5 nu = nu + half
```

• Similar options & more also from LLNL Fission package in MCNP6



LLNL fission model

- Fission neutrons & photons are correlated & have multiplicities
- Includes all multiplicity measurements from literature. Empirical models used if data are not available
- Neutrons and gammas sampled independently, no correlation
- Scales multiplicity data to match \bar{v} from evaluated data libraries
- Neutrons & gammas emitted isotropically

Neutron induced fission data

- 4 options for neutron multiplicity
 - Fit to Zucker-Holden data, 5th order polynomials in E_n
 - Same + Gwin-Spencer-Ingle data for ²³⁵U at thermal energies
 - Valentine polynomial fit of $P_v(v)$, Zucker-Holden & Gwin-Spencer-Ingle
 - Tables from Zucker-Holden & Gwin-Spencer-Ingle data, statistical selection to nearest nu-bar, or Terrell if nu-bar out of range
- Spectrum
 - Watt spectrum, TART scheme [b=1, fit a to poly in E_{in}]
- Neutron energy conservation, 3 options
 - Independent, no energy conservation
 - Sample total neutron energy from Gaussian, rescale each neutron E
 - Sample total neutron energy from quadratic fit, rescale each neutron E



Example — Watt Spectrum

$$f(x) = \frac{2e^{-ab/4}}{\sqrt{\pi a^3 b}} e^{-x/a} \sinh \sqrt{bx} , \quad 0 < x$$

Rejection (mcnp)

- Based on Algorithm R12 from 3rd Monte Carlo Sampler, Everett & Cashwell
- Define K = 1 + ab/8, $L = a \{K + (K^2 1)_{1/2}\}$, M = L/a 1

• Set
$$x \leftarrow -\log \xi_1$$
, $y \leftarrow -\log \xi_2$

1

• If $\{y - M(x+1)\}^2 \le bLx$, accept: return (Lx) otherwise, reject

Direct (new vim)

• Sample from Maxwellian in C-of-M, transform to lab $w \leftarrow a \left(-\log \xi_1 - \log \xi_2 \cos^2 \frac{\pi}{2} \xi_3 \right)$

$$x \leftarrow w + \frac{a^2b}{4} + (2\xi_4 - 1)\sqrt{a^2bw}$$

(assume isotropic emission from fission fragment moving with constant velocity in C-of-M)

Unpublished sampling scheme, based on original Watt spectrum derivation

Not widely known –

not used in MCNP



- For many years, patches to MCNP have existed for
 - Coincidence counting of fission neutrons
 - Plan to incorporate the patches permanently into public version
 - Intrinsic sources spontaneous fission
 - Plan to incorporate the patches permanently into public version

- List-mode data

- Can make use of exactly the same post-processing methods as for experimental data
- CGMF package will be added to MCNP6
- Investigate use of multiplicity for MCNP criticality calculations (KCODE)



Monte Carlo References

- 700+ technical reports, presentations, etc., are available from the MCNP website mcnp.lanl.gov, under "Reference Collection"
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